



**Technical Information** 

# **H1 Axial Piston Single Pumps** Size 060/068





# **Revision history**

# Table of revisions

Date	Changed	Rev
May 2017	NFPE gen. 3 changes.	0701
November 2015	Master Model Code changes.	0600
September 2014	MDC, CCO, and Swash Angle Sensor options added	FA
May 2014	Converted to Danfoss layout - DITA CMS	EA
Apr 2013	FDC option added	DA
Mar 2013	AC section updated	CA
Dec 2012	AC added	ВА
Nov 2010	First edition	AA



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# **H1 Pump General Specification**

Design	ixial piston pump of cradle swashplate design with variable displacement	
Direction of rotation	lockwise, Counterclockwise	
Pipe connections	Main pressure ports: ISO split flange boss Remaining ports: SAE straight thread O-ring boss	
Recommended installation position	Pump installation position is discretionary, however the recommended control position is on the top or at the side with the top position preferred.  If the pump is installed with the control at the bottom, flushing flow must be provided through port M14 located on the EDC, FNR and NFPE control.  Vertical input shaft installation is acceptable.  If input shaft is at the top 1 bar case pressure must be maintained during operation.  The housing must always be filled with hydraulic fluid.  Recommended mounting for a multiple pump stack is to arrange the highest power flow towards the input source.  Consult Danfoss for nonconformance to these guidelines.	
Auxiliary cavity pressure	Will be inlet pressure with internal charge pump. For reference see H1P 060/068 Operating Parameters.  Will be case pressure with external charge supply. Please verify mating pump shaft seal capability.	

# Technical data H1P 060/068

Feature	Size 060	Size 068
Displacement	60.4 cm <sup>3</sup> [3.69 in <sup>3</sup> ]	68.0 cm <sup>3</sup> [4.15 in <sup>3</sup> ]
Flow at rated (continuous) speed	210 l/min [55.5 US gal/min]	238 l/min [62.8 US gal/min]
Torque at maximum displacement (theoretical)	0.96 N·m/bar [590 lbf·in/1000psi ]	1.08 N·m/bar [610 lbf·in/1000psi]
Mass moment of inertia of rotating components	0.00709 kg•m² [0.00523 slug•ft²]	0.00707 kg•m² [0.00522 slug•ft²]
Mass [weight] dry	50 kg [110 lb] (without charge pump	o or auxiliary mounting flange)
Oil volume	2.1 l [0.55 US gal]	
Mounting flange	ISO 3019-1 flange 127-4 (SAE C)	
Input shaft outer diameter, splines and tapered shafts	ISO 3019-1, outer Ø32 mm - 4 (SAE C, 14 teeth) ISO 3019-1, outer Ø35 mm - 4 (SAE C, 21 teeth)	
Auxiliary mounting flange with metric fasteners Shaft outer diameter and splines	ISO 3019-1, flange 82 - 2, outer Ø16 mm - 4 (SAE A, 9 teeth) ISO 3019-1, flange 82 - 2, outer Ø19 mm - 4 (SAE A, 11 teeth) ISO 3019-1, flange 101 - 2, outer Ø22 mm - 4 (SAE B, 13 teeth) ISO 3019-1, flange 101 - 2, outer Ø25 mm - 4 (SAE B-B, 15 teeth) ISO 3019-1, flange 127 - 4, outer Ø32 mm - 4 (SAE C, 14 teeth)	
Suction port	ISO 11926-1 – 1 <sup>5</sup> / <sub>16</sub> –12 (SAE O-ring boss)	
Case drain ports L2, L4	ISO 11926-1 – 1 <sup>1</sup> / <sub>16</sub> –12 (SAE O-ring boss)	
Main port configuration	Ø25.4 - 450 bar split flange boss per ISO 6162, M12x1.75	
Other ports	SAE O-ring boss. See <i>Installation drawings</i> on page 46.	
Customer interface threads	Metric fasteners	

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# Operating parameters H1P 060/068

Feature		Size 060	Size 068
Input speed at minimum charge/	Minimum for internal <sup>1)</sup> and external <sup>2)</sup> charge supply	500 min <sup>-1</sup> (rpm)	
control pressure	Minimum for full performance for internal charge supply	1200 min <sup>-1</sup> (rpm)	
	Rated	3500 min <sup>-1</sup> (rpm)	
	Maximum	4000 min <sup>-1</sup> (rpm)	
System pressure	Maximum working pressure	420 bar [6090 psi]	380 bar [5510 psi]
	Maximum pressure	450 bar [6527 psi]	400 bar [5800 psi]
	Maximum low loop	45 bar [650 psi]	
	Minimum low loop pressure	10 bar [145 psi]	
Charge pressure	Minimum	14.5 bar [210 psi]	
	Maximum	34 bar [493 psi]	
Control pressure	Minimum at corner power for EDC, MDC, FNR	18.5 bar [270 psi]	
	Minimum at corner power for NFPE	26 bar [377 psi]	
	Maximum	40 bar [580 psi]	
Charge pump	Rated	0.7 bar (absolute) [9 in Hg vacuum]	
inlet pressure	Minimum (cold start)	0.2 bar (absolute) [24 in Hg vacuum]	
	Maximum	4 bar [58 psi]	
Case pressure	Rated	3 bar [44 psi]	
	Maximum	5 bar [73 psi]	
Lip seal external maxim	ium pressure	0.4 [5.8 psi]	

<sup>1)</sup> Performance (pressure and displacement) may be limited due to limited control pressure.

# **Fluid Specifications**

## Viscosity and Temperature range

Feature		Unit	Data
	Intermittent <sup>1)</sup>	mm²/s [ SUS]	5 [42]
Viscosity	Minimum		7 [49]
Viscosity	Recommended range		12 - 80 [66 - 370]
	Maximum		1600 [7500]
	Minimum <sup>3)</sup> (Cold start)		-40 [-40]
Temperature	Recommended range	]  °C[°F]	60 – 85 [140 – 185]
range <sup>2)</sup>	Rated	C[F]	104 [220]
	Maximum Intermittent <sup>1)</sup>		115 [240]

 $<sup>^{1)}</sup>$  Intermittent = Short term t < 1min per incident and not exceeding 2 % of duty cycle based load-life

<sup>&</sup>lt;sup>2)</sup> Full performance (pressure and displacement) possible at minimum charge and control pressure supply.

<sup>2)</sup> At the hottest point, normally case drain port

 $<sup>^{3)}</sup>$  Cold start = Short term t < 3 min, p  $\leq$  50 bar [725 psi], n  $\leq$  1000 min $^{-1}$  (rpm)



Filtration, Cleanliness level and Efficiency  $\beta_x$ -ratio (Recommended Minimum)

Cleanliness per ISO 4406	22/18/13
Efficiency $\beta_x$ (charge pressure filtration)	$\beta_{15-20} = 75 \ (\beta_{10} \ge 10)$
Efficiency $\beta_x$ (suction and return line Filtration)	$\beta_{35-45} = 75 \ (\beta_{10} \ge 2)$
Recommended inlet screen mesh size	100 – 125 μm

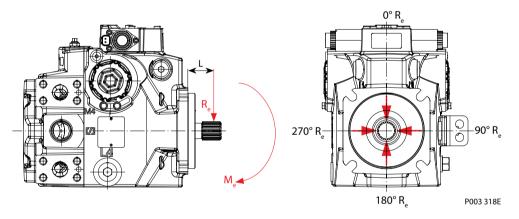
#### **External Radial Shaft Loads**

The pumps are designed with bearings that can accept some external radial loads. The external radial shaft load limits are a function of the load position and orientation, and the operating conditions of the unit. External radial shaft loads impact lifetime. For lifetime calculations please contact your Danfoss representative.

The maximum allowable radial load ( $R_e$ ) is based on the maximum external moment ( $M_e$ ) and the distance (L) from the mounting flange to the load. It may be determined using the following formula:

$$R_e = \frac{M_e}{I}$$

Radial load position



 $M_e$  = shaft moment

**L** = flange distance

 $\mathbf{R_e}$  = external force to the shaft

Thrust loads should be avoided. Contact your Danfoss representative in the event thrust loads are anticipated.

# Bearing life H1P 060/068

Maximum external shaft load based on shaft deflection

External radial moment	Unit	Size 060 / 068
M <sub>e</sub>	N•m [lbf•in]	104 [920]

All external shaft loads affect bearing life. In applications with external shaft loads, minimize the impact by positioning the load at  $0^{\circ}$  or  $180^{\circ}$  as shown in the figure.

Danfoss recommends clamp-type couplings for applications with radial shaft loads.

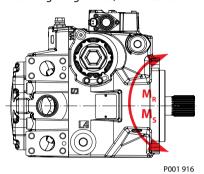
Contact your Danfoss representative for an evaluation of unit bearing life if you have continuously applied external loads exceeding 25 % of the maximum allowable radial load ( $R_e$ ) or the pump swashplate is positioned on one side of center all or most of the time.



# Mounting flange loads H1P 060/068

The moments shown below apply for top or side control orientation.

Mounting flange loads, Size 060/068



Rated moment: **M**<sub>R</sub> = 2110 N•m [18 680 lbf•in]

Shock load moment: M<sub>S</sub> = 5275 N·m [46 690 lbf·in]

For more information, see *H1 Axial Piston Pumps, Basic Information*, **BC00000057**, the section "Mounting flange loads".



## **Charge pump**

#### **Charge Pump Selection**

In most applications a general guideline is that the charge pump displacement should be at least 10% of the total displacement of all components in the system. Unusual application conditions may require a more detailed review of charge flow requirements. System features and conditions which may invalidate the 10% guideline include (but are not limited to):

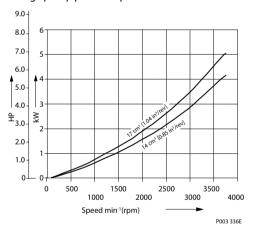
- Continuous operation at low input speeds < 1500 min<sup>-1</sup> (rpm)
- High shock loading and/or long loop lines
- · High flushing flow requirements
- Multiple low speed high torque motors
- High input shaft speeds

Contact your Danfoss representative for application assistance if your application includes any of these conditions.

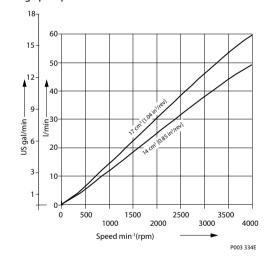
#### Charge pump flow and power curves, 14/17 cm<sup>3</sup>

Charge pressure: 20 bar [290 psi] Viscosity: 11 mm²/s [63 SUS] Temperature: 80°C [176°F]

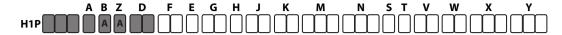
#### Charge pump power requirements



#### Charge pump flow







# Displacement

060	60.4 cm <sup>3</sup> [3.69 in <sup>3</sup> ]
068	68.0 cm <sup>3</sup> [4.15 in <sup>3</sup> ]

#### A – Rotation

I	L	Left hand (counter clockwise)
ı	R	Right hand (clockwise)

## B – Product version

С	Revision code
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# Z – Port configuration

Α	Inch, Customer O-ring port sealing according to ISO 11926-1
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# D – Controls — Electric Displacement Control (EDC)

Code	Control type	Voltage	MOR	CCO with key C	DEUTSCH Connector
A2	EDC	12 V	_	_	•
А3	EDC	24 V	_	_	•
A4	EDC	12 V	•	_	•
A5	EDC	24 V	•	_	•
E7	EDC	12 V	_	•	•
E8	EDC	24 V	_	•	•

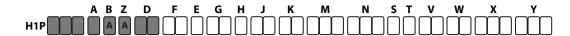
<sup>● –</sup> To be used for the control; — Not to be used for the control

# D – Controls (continued) — Non Feedback Proportional Electric Control (NFPE)

Code	Control type	Voltage	MOR	CCO with key C	Angle sensor	DEUTSCH Connector
N1	NFPE	12 V	•	_	_	•
N2	NFPE	24 V	•	_	_	•
N3	NFPE	12 V	_	•	•	•
N4	NFPE	24 V	_	•	•	•
N5	NFPE	12 V	•	_	•	•
N6	NFPE	24 V	•	_	•	•
N7	NFPE	12 V	_	•	_	•
N8	NFPE	24 V	_	•	_	•

Align with options: **E:** Displacement limiters and **W:** Special hardware.





## D – Controls — Automotive Control (AC)

Code	AC type	Voltage	MOR	Speed sensor	Wire harness	Angle sensor	DEUTSCH Connector
P6	AC-1	12 V	•	•	•	_	•
P7	AC-1	24 V	•	•	•	_	•
P8	AC-2	12 V	•	•	•	•	•
P9	AC-2	24 V	•	•	•	•	•
P5	AC-1	12 V	•	_	_	_	•
R3	AC-1	24 V	•	_	_	_	•
R4	AC-2	12 V	•	_	_	•	•
R5	AC-2	24 V	•	_	_	•	•

<sup>● –</sup> To be used for the control; — Not to be used for the control

## *D – Controls (continued) — Manual Displacement Control (MDC)*

Code	Control type	CCO Voltage	ссо	Neutral Start Switch	DEUTSCH Connector
M1	MDC	_	_	_	_
M2	MDC	_	_	•	•
МЗ	MDC	12 V	•	_	•
M4	MDC	24 V	•	_	•
M5	MDC	12 V	•	•	•
M6	MDC	24 V	•	•	•

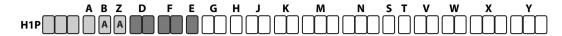
Align with options F: Orifices and Y: Settings for adjustment (if applicable).

#### D – Controls (continued) — Fan Drive Control (FDC)

Code	Control type	Voltage	DEUTSCH Connector
F1	FDC	12 V	•
F2	FDC	24 V	•

Align with options: F: Orifices, E: Displacement limiters, M, N: Overpressure protection, and W: Special hardware.





#### F – Orifices

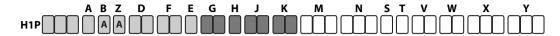
Code		Orifice		Controls: 1	To be used for (	•) / NOT to be	used for (–)
	Tank (A+B)	P	A/B	EDC, FNR	MDC	NFPE, AC	FDC
С3		No orifice		•	•	_	_
C1	-	_	0.8 mm	•	•	•	_
C2	-	-	1.3 mm	•	•	•	•
C4	-	-	1.8 mm	•	•	•	_
C6	1.0 mm	-	-	_	•	-	
C7	1.3 mm	-	_	_	•	-	_
C8	0.6 mm	0.8 mm	_	_	•	_	_
C9	0.6 mm	1.0 mm	-	-	•	-	-
D1	0.8 mm	1.0 mm	_	_	•	-	_
D2	0.8 mm	1.3 mm	_	_	•	_	_
D3	1.0 mm	1.3 mm	-	-	•	-	-
D4	1.0 mm	1.3 mm	1.3 mm	-	•	-	-
D5	0.6 mm	0.6 mm	0.8 mm	-	•	-	-
D8	-	-	2.3 mm	-	-	•	-

# E – Displacement limiter

N	None
С	No limiters, with nested springs, required for <b>NFPE, AC, FDC</b> *
В	Adjustable externally
D	Adjustable externally with nested springs, required for NFPE, AC, FDC*

<sup>\*</sup> Align with option Y: Settings for adjustment (if applicable).ima1444887758105





G – Endcap options (Twin port, ISO 6162 split flange ports)

# Align with options <u>T – Filtration</u> (below) and <u>K – Auxiliary mounting pads:</u>

- ISO 3019-1, flange 82-2 (SAE A, 9 and 11 teeth)
- ISO 3019-1, flange 101-2 (SAE B, 13 teeth)
- ISO 3019-1, flange 101-2 (SAE B-B, 15 teeth) or None

	· · · · · · · · · · · · · · · · · · ·	,	
Code	Suction filtration	Integral full charge flow filtration	Remote or external charge supply for full charge flow filtration
D3	-	•	-
D6	•	-	-
D8	-	-	•
Align w	th option <u>K - Auxiliary mounting</u>	<i>pad:</i> ISO 3019-1, flange 127–4 (SA	E C, 14 teeth)
F4	-	•	-
F5	-	-	•
F6	•	-	-

#### H – Mounting

н	ISO 3019-1, flange 127–4 (SAE C)
K	ISO 3019-1, flange 127–4 (SAE C), 4-bolt and speed sensor

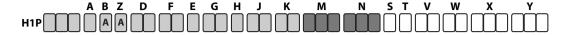
#### J – Input shaft

G1	ISO 3019-1, outer Ø32 mm - 4 (SAE C, 14 teeth splined shaft 12/24 pitch)
F1	ISO 3019-1, outer Ø35 mm - 4 (SAE C, 21 teeth splined shaft 16/32 pitch)

# K – Auxiliary mounting pad per ISO 3019-1 (Align with option G: Endcap selection)

NN	None	
H1	Flange 82–2, outer Ø19 mm - 4 (SAE A, 11 teeth 16/32 coupling)	
H2	Flange 82–2, outer Ø16 mm - 4 (SAE A, 9 teeth 16/32 coupling)	
НЗ	Flange 101–2, outer Ø22 mm - 4 (SAE B, 13 teeth 16/32 coupling)	Shipping cover
Н5	Flange 101–2, outer Ø25 mm - 4 (SAE B-B, 15 teeth 16/32 coupling)	
Н6	Flange 127–4, outer Ø32 mm - 4 (SAE C, 14 teeth 12/24 coupling)	





M – Overpressure protection type, side "A" / N – Overpressure protection type, side "B"

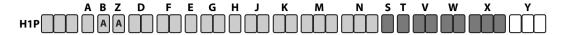
Pressure limiter and HPRV with bypass, pressure protection type <u>must be the same</u> for side "A" and "B"				
Pressure limiter setting	HPRV setting			
150 bar [2900 psi]	200 bar [2900 psi]			
180 bar [2610 psi]	250 bar [3630 psi]			
200 bar [2900 psi]	250 bar [3630 psi]			
230 bar [3336 psi]	280 bar [4061 psi]			
250 bar [3630 psi]	300 bar [4350 psi]			
280 bar [4061 psi]	330 bar [4786 psi]			
300 bar [4350 psi]	350 bar [5080 psi]			
330 bar [4786 psi]	380 bar [5510 psi]			
350 bar [5080 psi]	400 bar [5800 psi]			
380 bar [5510 psi] 420 bar [6090 psi]				
400 bar [5800 psi] (Available for 060 <u>only</u> .)	450 bar [6526 psi]			
420 bar [6090 psi] (Available for 060 <u>only</u> .)	450 bar [6526 psi]			
verpressure protection type and setting for FDC				
150 bar [2175 psi]	250 bar [3630 psi]			
150 bar [2175 psi]	300 bar [4350 psi]			
150 bar [2175 psi]	350 bar [5080 psi]			
	Pressure limiter setting   150 bar [2900 psi]   180 bar [2610 psi]   200 bar [2900 psi]   230 bar [2900 psi]   230 bar [3336 psi]   250 bar [3630 psi]   280 bar [4061 psi]   300 bar [4350 psi]   330 bar [4786 psi]   350 bar [5080 psi]   380 bar [5510 psi]   400 bar [5800 psi] (Available for 060 only.)   420 bar [6090 psi] (Available for 060 only.)   essure protection type and setting for FDC   150 bar [2175 psi]   150 bar [2175 psi]			

	essure setting <sup>2)</sup> 0 bar [2610 psi] 0 bar [2900 psi]
<b>K18</b> 180	
	0 har [2000 noi]
<b>K20</b> 200	o nai (2200 psi)
<b>K23</b> 230	0 bar [3336 psi]
<b>K25</b> 250	0 bar [3630 psi]
<b>K28</b> 280	0 bar [4061 psi]
<b>K30</b> 300	0 bar [4350 psi]
<b>K33</b> 330	0 bar [4786 psi]
<b>K35</b> 350	0 bar [5080 psi]
<b>K38</b> 380	0 bar [5510 psi]
<b>K40</b> 400	0 bar [5800 psi] (Available for 060 <u>only</u> .)
<b>K42</b> 420	0 bar [6090 psi] (Available for 060 <u>only</u> .)

<sup>1)</sup> L, F – with pressure limiter; K – without pressure limiter.

 $<sup>^{2)}\,</sup>Please\,contact\,Danfoss\,for\,pressures\,not\,shown\,or\,for\,applied\,pressure\,above\,max.\,working\,pressure.$ 





# S – Charge pump

F	14 cm³/rev [0.85 in³/rev]
С	17 cm³/rev [1.03 in³/rev]
N	No charge pump, external charge supply (Align with options: <b>E</b> and <b>T</b> )

# *T – Filtration (Align with option G – Endcap selection)*

L	Suction filtration (see H1P 060/068, suction filtration, option L on page 60)
М	Integral full charge flow filtration with bypass, bypass sensor, medium filter length, 11004918
P	Remote full charge flow filtration
E	External charge flow filtration (Align with options: <b>N</b> and <b>S</b> )

# V – Charge pressure relief setting

18	18 bar [261 psi]	
20	20 bar [290 psi]	Next a he wood for NEDE AC and EDC controls
22	22 bar [319 psi]	Not to be used for NFPE, AC and FDC controls.
24	24 bar [348 psi]	
26	26 bar [377 psi]	
28	28 bar [406 psi]	
30	30 bar [435 psi]	
32	32 bar [464 psi]	
34	34 bar [493 psi]	

# W – Special hardware features

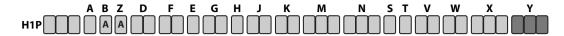
PN	EDC / FNR / MDC valve plate
P1	NFPE valve plate (Align with options: <b>D</b> and <b>E</b> )
P2	NFPE / FDC / AC valve plate and speed ring on the cylinder block
P4	EDC / FNR / MDC valve plate with speed ring on the cylinder block (Align with options: <b>D</b> and <b>E</b> )
H1	MDC / EDC / FNR valve plate with MDC handle

# X – Paint and nametag

NNN	Black paint and Danfoss nametag
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Y – Special settings (SIL–2 non-certifiable, without customer files)

Code	CAN J1939	ECO fuel saving mode	Functional option	Cruise control	Control	AC type
D3E	in/out	•	Е	-	N1 (12 V <sub>DC</sub> ) N2 (24 V <sub>DC</sub> )	- AC-1
D3F	in/out	-	F	-		
D4E	in/out	•	Е	-		
D4F	in/out	-	F	-		
D5F	in/out	-	F	-	P8 (12 V <sub>DC</sub> ) P9 (24 V <sub>DC</sub> )	AC–2 with Swash Plate Angle Sensor
D5J	in/out	•	J	•		
D6F	in/out	-	F	-		
D6J	in/out	•	J	•		
МОО	MDC handle sta	andard position	•			
NNN	None					

<sup>=</sup> available option

<sup>– =</sup> not available option



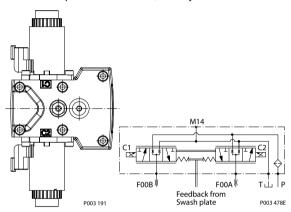
## **Electrical Displacement Control (EDC)**

The Electrical Displacement Control (EDC) consists of a pair of proportional solenoids on each side of a three-position, four-way porting spool. The proportional solenoid applies a force input to the spool, which ports hydraulic pressure to either side of a double acting servo piston.

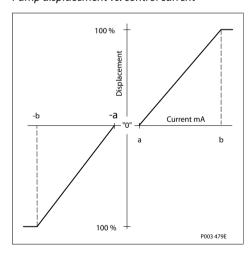
Differential pressure across the servo piston rotates the swashplate, changing the pump's displacement from full displacement in one direction to full displacement in the opposite direction.

Under some circumstances, such as contamination, the control spool could stick and cause the pump to stay at some displacement. A serviceable 125  $\mu m$  screen is located in the supply line immediately before the control porting spool.

Electrical Displacement Control, with hydraulic schematic



Pump displacement vs. control current



## **EDC Control Signal Requirements**

Control minimum current to stroke pump

Voltage	a*	b	Pin connections
12 V	640 mA	1640 mA	any order
24 V	330 mA	820 mA	

Factory test current, for vehicle movement or application actuation expect higher or lower value.





#### Connector ordering data

Description	Quantity	Ordering data
Mating connector	1	DEUTSCH DT06-2S
Wedge lock	1	DEUTSCH W2S
Socket contact (16 and 18 AWG)	2	DEUTSCH 0462-201-16141
Danfoss mating connector kit	1	K29657

#### **EDC Solenoid Data**

Description		12 V	24 V		
Maximum current		1800 mA	920 mA		
Nominal coil resistance	@ 20 °C [68 °F]	3.66 Ω	14.20 Ω		
	@ 80 °C [176 °F]	4.52 Ω	17.52 Ω		
Inductance	Inductance		140 mH		
PWM signal frequency	Range	70 – 200 Hz	70 – 200 Hz		
	Recommended*	200 Hz	200 Hz		
IP Rating	IP Rating IEC 60 529		IP 67		
DIN 40 050, part 9		IP 69K with mating	IP 69K with mating connector		
Connector color		Black	Black		

<sup>\*</sup> PWM signal required for optimum control performance.

## Pump output flow direction vs. control signal

Shaft rotation	CW		ccw	
Coil energized*	C1	C2	C1	C2
Port A	out	in	in	out
Port B	in	out	out	in
Servo port pressurized	M4	M5	M4	M5

<sup>\*</sup> For coil location see Installation drawings.

#### **Control Response**

H1 controls are available with optional control passage orifices to assist in matching the rate of swashplate response to the application requirements (e.g. in the event of electrical failure). The time required for the pump output flow to change from zero to full flow (acceleration) or full flow to zero (deceleration) is a net function of spool porting, orifices, and charge pressure. A swashplate response table is available for each frame indicating available swashplate response times. Testing should be conducted to verify the proper orifice selection for the desired response.

H1 pumps are limited in mechanical orificing combinations. Mechanical servo orifices are to be used only for fail-safe return to neutral in the event of an electrical failure.

#### Typical response times at the following conditions:

Δр	250 bar [3626 psi]
Viscosity and temperature	30 mm <sup>2</sup> /s [141 SUS] and 50 °C [122 °F]

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Typical response times at the following conditions: (continued)

Charge pressure	20 bar [290 psi]
Speed	1800 min <sup>-1</sup> (rpm)

# Response time, EDC 060/068

Stroking direction	0.8 mm [0.03 in] Orifice	1.3 mm [0.05 in] Orifice	No orifice	
Neutral to full flow	2.6 s	1.2 s	0.8 s	
Full flow to neutral	1.7 s	0.8 s	0.4 s	



#### **Manual Displacement Control (MDC)**

A Manual proportional Displacement Control (**MDC**) consists of a handle on top of a rotary input shaft. The shaft provides an eccentric connection to a feedback link. This link is connected on its one end with a porting spool. On its other end the link is connected the pumps swashplate.

This design provides a travel feedback without spring. When turning the shaft the spool moves thus providing hydraulic pressure to either side of a double acting servo piston of the pump.

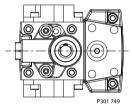
Differential pressure across the servo piston rotates the swash plate, changing the pump's displacement. Simultaneously the swashplate movement is fed back to the control spool providing proportionality between shaft rotation on the control and swashplate rotation.

The MDC changes the pump displacement between no flow and full flow into opposite directions. Under some circumstances, such as contamination, the control spool could stick and cause the pump to stay at some displacement.

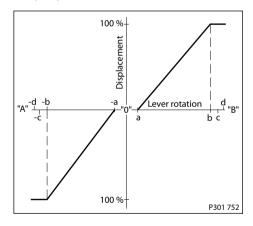
A serviceable 125 µm screen is located in the supply line immediately before the control porting spool.

The MDC is sealed by means of a static O-ring between the actuation system and the control block. Its shaft is sealed by means of a special O-ring which is applied for low friction. The special O-ring is protected from dust, water and aggressive liquids or gases by means of a special lip seal.

Manual Displacement Control



Pump displacement vs. control lever rotation



#### Legend:

Deadband on **B** side –  $\mathbf{a} = 3^{\circ} \pm 1^{\circ}$ Maximum pump stroke –  $\mathbf{b} = 30^{\circ} + 2/-1^{\circ}$ Required customer end stop –  $\mathbf{c} = 36^{\circ} \pm 3^{\circ}$ Internal end stop –  $\mathbf{d} = 40^{\circ}$ 

#### **MDC Torque**

Description	Value
Torque required to move handle to maximum displacement	1.4 N·m [12.39 lbf·in ]
Torque required to hold handle at given displacement	0.6 N·m [5.31 lbf·in]
Maximum allowable input torque	20 N•m [177 lbf•in]





#### Caution

Volumetric efficiencies of the system will have impacts on the start and end input commands.

#### **MDC General Information**

In difference to other controls the MDC provides a mechanical deadband. This is required to overcome the tolerances in the mechanical actuation.

The MDC contains an internal end stop to prevent over travel. The restoring moment is appropriate for turning the MDC input shaft back to neutral only. Any linkages or cables may prevent the MDC from returning to neutral.

The MDC is designed for a maximum case pressure of 5 bar and a rated case pressure of 3 bar. If the case pressure exceeds 5 bar there is a risk of an insufficient restoring moment. In addition a high case pressure can cause the NSS to indicate that the control is not in neutral. High case pressure may cause excessive wear.

Customers can apply their own handle design but they must care about a robust clamping connection between their handle and the control shaft and avoid overload of the shaft.

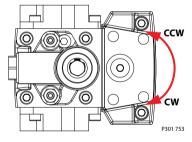
Customers can connect two MDC's on a tandem unit in such a way that the actuation force will be transferred from the pilot control to the second control but the kinematic of the linkages must ensure that either control shaft is protected from torque overload. To avoid an overload of the MDC, customers must install any support to limit the setting range of the Bowden cable.



#### Caution

Using the internal spring force on the input shaft is not an appropriate way to return the customer connection linkage to neutral.

#### **MDC Shaft Rotation**



#### MDC shaft rotation data

Pump shaft rotation*	Clock Wise (CW)		Counter Clock Wise (CCW)		
MDC shaft rotation	CW CCW		cw	ccw	
Port A	in (low)	out (high)	out (high)	in (low)	
Port B	out (high)	in (low)	in (low)	out (high)	
Servo port high pressure	M5	M4	M5	M4	

As seen from shaft side.

## **Control Response**

H1 controls are available with optional control passage orifices to assist in matching the rate of swashplate response to the application requirements (e.g. in the event of electrical failure). The time required for the pump output flow to change from zero to full flow (acceleration) or full flow to zero (deceleration) is a net function of spool porting, orifices, and charge pressure. A swashplate response table is available for each frame indicating available swashplate response times. Testing should be conducted to verify the proper orifice selection for the desired response.



H1 pumps are limited in mechanical orificing combinations. Mechanical servo orifices are to be used only for fail-safe return to neutral in the event of an electrical failure.

Typical response times at the following conditions:

Δр	250 bar [3626 psi]			
Viscosity and temperature	30 mm <sup>2</sup> /s [141 SUS] and 50 °C [122 °F]			
Charge pressure	20 bar [290 psi]			
Speed	1800 min <sup>-1</sup> (rpm)			

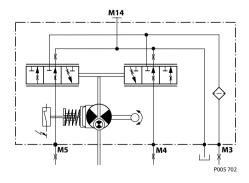
## Response time, MDC 060/068

Code		Orifice description (mm)			Stroking direction (sec)		
	Р	A	В	Tank (A+B)	Neutral to full flow	Full flow to neutral	
С3	-	-	-	-	0.4	0.4	
C6	-	-	_	1	1.1	1.0	
C7	-	-	_	1.3	0.7	0.7	
C8	0.8	_	_	0.6	3.6	2.6	
C9	1	-	-	0.6	3.3	2.4	
D1	1	-	_	0.8	2.1	1.5	
D2	1.3	_	_	0.8	1.8	1.4	
D3	1.3	-	-	1	1.3	1.0	
D4	1.3	1.3	1.3	1	1.6	1.2	
D5	0.6	0.8	0.8	0.6	6.5	3.6	

## **Neutral Start Switch (NSS)**

The Neutral Start Switch (NSS) contains an electrical switch that provides a signal of whether the control is in neutral. The signal in neutral is Normally Closed (NC).

Neutral Start Switch schematic



## Neutral Start Switch data

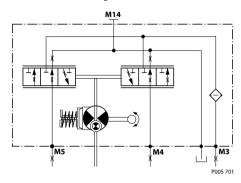
Max. continuous current with switching	8.4 A
Max. continuous current without switching	20 A
Max. voltage	36 V <sub>DC</sub>
Electrical protection class	IP67 / IP69K with mating connector



# Case Gauge Port M14

The drain port should be used when the control is mounted on the unit's bottom side to flush residual contamination out of the control.

MDC schematic diagram



#### Lever

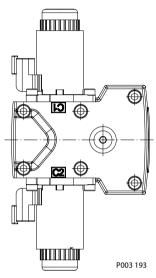
MDC-controls are available with an integrated lever.

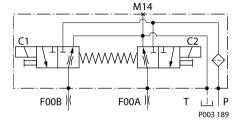


# Forward-Neutral-Reverse electric control (FNR), options: A9 (12 V) and B1 (24 V)

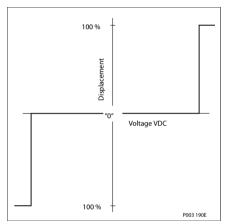
The 3-position **FNR** control uses an electric input signal to switch the pump to a full stroke position. Under some circumstances, such as contamination, the control spool could stick and cause the pump to stay at some displacement. A serviceable 125  $\mu$ m screen is located in the supply line immediately before the control porting spool.

Forward-Neutral-Reverse electric control (FNR) FNR hydraulic schematic



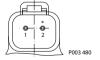


Pump displacement vs. electrical signal



## Control current

Voltage	Min. current to stroke pump	Pin connections
12 V	750 mA	any order
24 V	380 mA	



#### Connector ordering data

Description	Quantity	Ordering data
Mating connector	1	DEUTSCH DT06-2S
Wedge lock	1	DEUTSCH W2S
Socket contact (16 and 18 AWG)	2	DEUTSCH 0462-201-16141
Danfoss mating connector kit	1	K29657



#### Solenoid data

Voltage	12 V	24 V	
Minimum supply voltage	9.5 V <sub>DC</sub>	19 V <sub>DC</sub>	
Maximum supply voltage (continuous)	14.6 V <sub>DC</sub>	29 V <sub>DC</sub>	
Maximum current	1050 mA	500 mA	
Nominal coil resistance @ 20 °C [70 °F]	8.4 Ω	34.5 Ω	
PWM Range	70-200 Hz		
PWM Frequency (preferred)*	100 Hz		
IP Rating (IEC 60 529) + DIN 40 050, part 9	IP 67 / IP 69K (part 9 with mating connector)		
Bi-directional diode cut off voltage	28 V <sub>DC</sub>	53 V <sub>DC</sub>	

<sup>\*</sup> PWM signal required for optimum control performance.

#### Pump output flow direction vs. control signal

Shaft rotation	CW		ccw	
Coil energized*	C1 C2		C1	C2
Port A	in	out	out	in
Port B	out	in	in	out
Servo port pressurized	M5	M4	M5	M4

<sup>\*</sup> For coil location see *Installation drawings* on page 46.

#### **Control Response**

H1 controls are available with optional control passage orifices to assist in matching the rate of swashplate response to the application requirements (e.g. in the event of electrical failure). The time required for the pump output flow to change from zero to full flow (acceleration) or full flow to zero (deceleration) is a net function of spool porting, orifices, and charge pressure. A swashplate response table is available for each frame indicating available swashplate response times. Testing should be conducted to verify the proper orifice selection for the desired response.

H1 pumps are limited in mechanical orificing combinations. Mechanical servo orifices are to be used only for fail-safe return to neutral in the event of an electrical failure.

# Typical response times at the following conditions:

Δр	250 bar [3626 psi]	
Viscosity and temperature	30 mm <sup>2</sup> /s [141 SUS] and 50 °C [122 °F]	
Charge pressure	20 bar [290 psi]	
Speed	1800 min <sup>-1</sup> (rpm)	

#### FNR response time 060/068

Stroking direction	0.8 mm [0.03 in] orifice	1.3 mm [0.05 in] orifice	No orifice
Neutral to full flow	2.2 s	1.0 s	1.1 s
Full flow to neutral	2.0 s	0.9 s	0.8 s

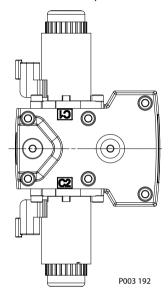


## Non Feedback Proportional Electric Control (NFPE)

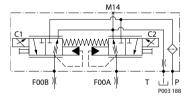
The Non Feedback Proportional Electric (**NFPE**) control is an electrical automotive control in which an electrical input signal activates one of two proportional solenoids that port charge pressure to either side of the pump servo cylinder. The NFPE control has no mechanical feedback mechanism.

A serviceable 170 µm screen is located in the supply line immediately before the control porting spool.

Non Feedback Proportional Electric Control



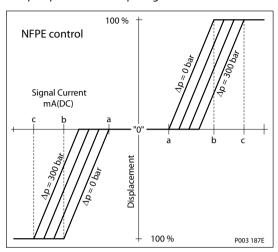
## NFPE schematic



The pump displacement is proportional to the solenoid signal current, but it also depends upon pump input speed and system pressure. This characteristic also provides a power limiting function by reducing the pump swashplate angle as system pressure increases. A typical response characteristic is shown in the accompanying graph. Under some circumstances, such as contamination, the control spool could stick and cause the pump to stay at some displacement.



# Pump displacement vs. input signal



# Control Signal Requirements, NFPE 060/068

#### Control current

Voltage	a*	b	с	Pin connections
12 V	694 mA	1114 mA	1490 mA	any order
24 V	347 mA	583 mA	745 mA	

<sup>\*</sup> Factory test current, for vehicle movement or application actuation expect higher or lower value.



# Connector ordering data

Description	Quantity	Ordering data
Mating connector	1	DEUTSCH DT06-2S
Wedge lock	1	DEUTSCH W2S
Socket contact (16 and 18 AWG)	2	DEUTSCH 0462-201-16141
Danfoss mating connector kit	1	K29657

Description		12 V	24 V
Maximum current		1800 mA	920 mA
Nominal coil resistance	@ 20 °C [68 °F]	3.66 Ω	14.20 Ω
	@ 80 °C [176 °F]	4.52 Ω	17.52 Ω
Inductance		33 mH	140 mH
PWM signal frequency	Range	70 – 200 Hz	
	Recommended*	200 Hz	
IP Rating	IEC 60 529	IP 67	
DIN 40 050, part 9		IP 69K with mating connector	
Connector color		Black	

<sup>\*</sup> PWM signal required for optimum control performance.

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#### Pump output flow direction vs. control signal

Shaft rotation	cw		ccw	
Coil energized*	C1	C2	C1	C2
Port A	in	out	out	in
Port B	out	in	in	out
Servo port pressurized	M5	M4	M5	M4

<sup>\*</sup> For coil location see Installation drawings.

## **Control Response**

H1 controls are available with optional control passage orifices to assist in matching the rate of swashplate response to the application requirements (e.g. in the event of electrical failure). The time required for the pump output flow to change from zero to full flow (acceleration) or full flow to zero (deceleration) is a net function of spool porting, orifices, and charge pressure. A swashplate response table is available for each frame indicating available swashplate response times. Testing should be conducted to verify the proper orifice selection for the desired response.

H1 pumps are limited in mechanical orificing combinations. Mechanical servo orifices are to be used only for fail-safe return to neutral in the event of an electrical failure.

#### *Typical response times at the following conditions:*

Δр	250 bar [3626 psi]	
Viscosity and temperature	30 mm <sup>2</sup> /s [141 SUS] and 50 °C [122 °F]	
Charge pressure	20 bar [290 psi]	
Speed	1800 min <sup>-1</sup> (rpm)	

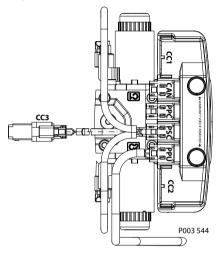
## Response Time, NFPE 060/068

Stroking direction	0.8 mm [0.03 in] orifice	1.3 mm [0.05 in] orifice	2.3 mm [0.09 in] orifice
Neutral to full flow	2.5 s	1.1 s	0.6 s
Full flow to neutral	1.9 s	0.6 s	0.3 s



#### **Automotive Control (AC)**

The H1 **A**utomotive **C**ontrol (AC) is an electric NFPE Control with an integrated microcontroller, installed on the pump. The integrated microcontroller enhanced control performance with a flexible, configurable control scheme for an entire single path propel transmission. It can be used in combination with fixed and variable displacement hydraulic-motors. With the pre-installed application software and easily changeable control parameters, it is possible to tailor the vehicle's driving behavior to the individual requirements of the customer.



The H1 Automotive Control is divided into 2 systems:

- AC-1
- AC-2

AC-2 is an extension of AC-1 that features an integrated pump swash plate angle sensor and software enabled functions such as Swash Plate Control.

## **Mode types**

The application software provides 3 different hydrostatic propel methods, defined as mode types, which can be used individually.

- Automotive Load dependent (torque controlled) driving behavior. Setpoint for the drive curve is
  the engine rpm.
- Non-Automotive Load independent (speed controlled) driving mode. Setpoint for the drive curve is a Joystick or drive pedal signal, independent of the engine rpm. The best performance will achieved with an AC-2 Swash Plate Angle Sensor.
- Creep-Automotive Load dependent (torque controlled) driving behavior (like Automotive). Setpoint for the drive curve is the engine rpm. The setpoint can be reduced by the creep potentiometer if a high engine rpm in combination with low vehicle speed is needed.

#### **Basic functions**

- Four selectable system modes, selectable via switch.
- Individual settings for forward and reverse driving direction (4 x 2 curves).
- Independent pump and hydraulic-motor profiling and ramping for each mode.
- Electric drive pedal connection
- Electronic inching function without separate control valve
- Electric creep mode potentiometer



- Configurable System Mode & Direction change
- Load independent pump displacement control with integrated Swash Plate Angle Sensor (AC-2)
- Hydraulic-motor displacement control including brake pressure defeat function

#### **Performance functions**

- · ECO fuel saving mode with automatic reduction of the engine speed during transport (Cruise control)
- Vehicle constant speed drive control
- Vehicle speed limitation
- Dynamic brake light, automatic park brake, reverse buzzer and status LED outputs
- Vehicle speed controlled output function.
- · Temperature compensation for predictable performance
- · Advanced CAN J1939 interface for the information exchange with the vehicle control system

#### **Protection and safety functions**

- Safety controlled vehicle start protection with engine speed check, battery check and FNR must be in neutral, etc..
- Operator presence detection
- Hydraulic system overheat and low-temperature protection
- Hydraulic motor over speed protection
- Park brake test mode for roller applications to fulfill SAE J1472 / EN500-4.
- SIL2 compliant

#### **Engine control and protection**

- CAN J1939 engine interface
- · Engine speed control via drive pedal with safety controlled monitoring function
- · Engine antistall protection
- Engine over speed protection during inching
- Engine speed dependent Retarder control
- Engine cold start protection

#### **Installation features**

- · Factory calibration for hysteresis compensation.
- Starting current adjustment in the factory
- Pre-installed application software and parameter files

For more information, see Automotive Control for H1 SIngle Pumps Technical Information, BC00000213.

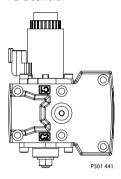


#### Fan Drive Control (FDC)

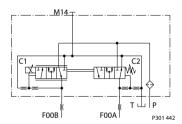
The Fan Drive Control (**FDC**) is a non-feedback control in which an electrical input signal activates the proportional solenoid that ports charge pressure to either side of the pump servo cylinder. The single proportional solenoid is used to control pump displacement in the forward or reverse direction. The control spool is spring biased to produce maximum forward pump displacement in the absence of an electrical input signal. Based on the spring bias spool default forward flow for a CW rotation pump is out of Port B while default forward flow for a CCW rotation pump is out of Port A.

The pump displacement is proportional to the solenoid signal current, but it also depends upon pump input speed and system pressure. This characterisistic also provides a power limiting function by reducing the pump swashplate angle as sytem pressure increases. The pump should be configured with 0.8 mm control orifices to provide slowest response and maximize system stability. Additionally pressure limiter (PL) valves are used to limit maximum fan trim speed in both (forward and reverse) directions.

#### FDC control



FDC hydraulic schematic



H1 pumps with FDC will be delivered from factory with nominal PL setting of 150 bar [2175 psi]. The PL must be re-adjusted to ensure that the fan reaches the desired fan speed to satisfy the cooling needs of the system. HPRV setting must be always at least 30 bar [435 psi] higher than PL setting.

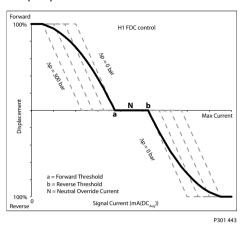
Under some circumstances, such as contamination, the control spool could stick and cause the pump to stay at some displacement.

For more information necessary to properly size and configure a hydraulic fan drive system, see *Hydraulic Fan Drive Design Guidelines* **AB00000019**.

Use in other systems could result in unintended movement of the machine or it's elements. Loss of the input signal to this control will cause the pump to produce maximum flow. The FDC is for Fan Drive systems only!



## Pump displacement vs. control current



## **Control Response**

H1 controls are available with optional control passage orifices to assist in matching the rate of swashplate response to the application requirements (e.g. in the event of electrical failure). The time required for the pump output flow to change from zero to full flow (acceleration) or full flow to zero (deceleration) is a net function of spool porting, orifices, and charge pressure. A swashplate response table is available for each frame indicating available swashplate response times. Testing should be conducted to verify the proper orifice selection for the desired response.

H1 pumps are limited in mechanical orificing combinations. Mechanical servo orifices are to be used only for fail-safe return to neutral in the event of an electrical failure.

Typical response times at the following conditions:

Δр	250 bar [3626 psi]
Viscosity and temperature	30 mm <sup>2</sup> /s [141 SUS] and 50 °C [122 °F]
Charge pressure	20 bar [290 psi]
Speed	1800 min <sup>-1</sup> (rpm)

## Response time, FDC

Stroking direction	0.8 mm [0.03 in] orifice
Full flow to neutral	2.6 s
Full forward flow to full reverse flow	3.7 s

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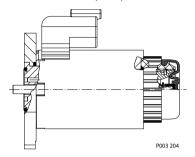


#### Manual Over Ride (MOR)

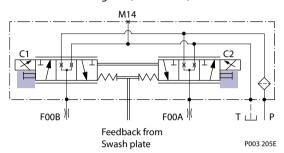
All controls are available with a Manual Over Ride (MOR) either standard or as an option for temporary actuation of the control to aid in diagnostics.

Forward-Neutral-Reverse (FNR) and Non Feedback Proportional Electric (NFPE) controls are always supplied with MOR functionality.

#### Manual OverRide (MOR)



#### MOR schematic diagram (EDC shown)



Unintended MOR operation will cause the pump to go into stroke. The vehicle or device must always be in a "safe" condition (i.e. vehicle lifted off the ground) when using the MOR function.

The MOR plunger has a 4 mm diameter and must be manually depressed to be engaged. Depressing the plunger mechanically moves the control spool which allows the pump to go on stroke.

The MOR should be engaged anticipating a full stroke response from the pump.



#### Warning

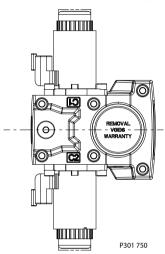
An o-ring seal is used to seal the MOR plunger where initial actuation of the function will require a force of 45 N to engage the plunger. Additional actuations typically require less force to engage the MOR plunger. Proportional control of the pump using the MOR should not be expected.

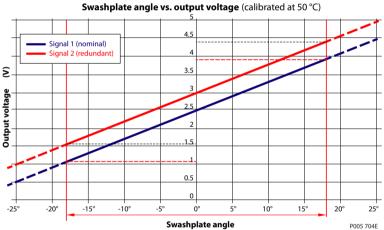
Refer to control flow table for the relationship of solenoid to direction of flow.



# Swash plate angle sensor for NFPE and AC2 controls

The angle sensor detects the swash plate angle position and direction of rotation from the zero position. The swash angle sensor works on the AMR sensing technology. Under the saturated magnetic field, the resistance of the element varies with the magnetic field direction. The output signal give a linear output voltage for the various magnet positions in the sensing range. The swashplate angle sensor is available for all NFPE and AC2 controls.





#### **Swash Plate Angle Sensor Parameters**

Parameter	Minimum	Typical	Maximum
Supply voltage range	4.75 V	5 V	5.25 V
Supply protection	-	-	28 V
Supply current	-	22 mA	25 mA
Output current (Signal 1, 2)	-	0.1 mA	-
Short circuit output current to supply or GND <sup>1)</sup>	-	-	7.5 mA
Sensitivity	70.0 mV/deg	78.0 mV/deg	85.8 mV/deg
Working range (swashplate angle)	-18°C	0°C	18°C
Correlation between signals 1 and 2 <sup>2)</sup>	475 mV	500 mV	525 mV

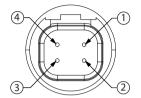
<sup>1)</sup> Up to duration of 2.5 seconds at 25°C

<sup>&</sup>lt;sup>2)</sup> Signal 1 (nominal) is lower than signal 2 (redundant)



# Swash plate angle sensor connector

## Pin assignment



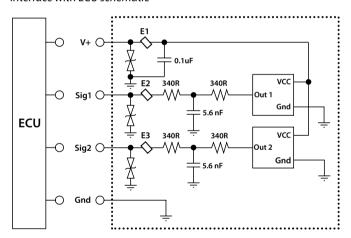
- 1. Ground (GND)
- Ground (GND)
   Output Signal 2 (SIG2) Secondary (redundant)
   Output Signal 1 (SIG1) Primary (nominal)
   Supply (V+)

#### Swash angle sensor connector order numbers

Description	Quantity	Ordering number
Mating connector DEUTSCH DTM06-4S-E004	1	11105824
Wedge lock DEUTSCH W4S	1	11084558
Socket contact (16-18 AWG)DEUTSCH 0462-201-16141	2	K02325

#### Interface with ECU

Interface with ECU schematic



Minimum recommended load resistance is 100 k $\Omega$ .



#### **Control-Cut-Off valve (CCO valve)**

The H1 pump offers an optional control cut off valve integrated into the control. This valve will block charge pressure to the control, allowing the servo springs to de-stroke both pumps regardless of the pump's primary control input. There is also a hydraulic logic port, X7, which can be used to control other machine functions, such as spring applied pressure release brakes. The pressure at X7 is controlled by the control cut off solenoid. The X7 port would remain plugged if not needed.

In the normal (de-energized) state of the solenoid charge flow is prevented from reaching the controls. At the same time the control passages and the X7 logic port are connected and drained to the pump case. The pump will remain in neutral, or return to neutral, independent of the control input signal. Return to neutral time will be dependent on oil viscosity, pump speed, swashplate angle, and system pressure.

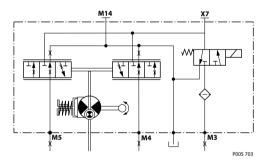
When the solenoid is energized, charge flow and pressure is allowed to reach the pump control. The X7 logic port will also be connected to charge pressure and flow.

The solenoid control is intended to be independent of the primary pump control making the control cut off an override control feature. It is however recommended that the control logic of the CCO valve be maintained such that the primary pump control signal is also disabled whenever the CCO valve is deenergized. Other control logic conditions may also be considered.

All EDC and MDC controls are available with a CCO valve. The CCO-valve is available with  $12\,\mathrm{V}$  or  $24\,\mathrm{V}$  solenoid.

The response time of the unit depends on the control type and the used control orifices.

#### CCO schematic (MDC shown)



#### **CCO** connector



#### Connector ordering data

Description	Quantity	Ordering number	
Mating connector	1	DEUTSCH DT06-2S	
Wedge lock	1	DEUTSCH W2S	
Socket contact (16 and 18 AWG)	2	DEUTSCH 0462-201-16141	

## **CCO** solenoid data

Nominal supply voltage		12 V	24 V
Supply voltage	oltage Maximum	14.6 V	29 V
	Minimum	9.5 V	19 V
Nominal coil resistance at 20°C		10.7 Ω	41.7 Ω



# **Control Options**

Nominal supply voltage	12 V	24 V	
Supply current	Maximum	850 mA	430 mA
	Minimum	580 mA	300 mA
PWM frequency Range		50-200 Hz	50-200 Hz
	Preferred	100 Hz	100 Hz
Electrical protection class		IP67 / IP69K with n	nating connector
Bi-directional diode cut off voltage		28 V	53 V

# Brake gauge port with MDC



## Caution

It is not recommended to use brake port for any external flow consumption to avoid malfunction of CCO function.

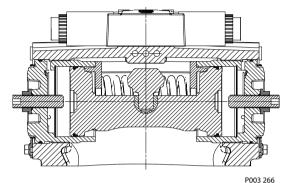


### **Control Options**

## **Displacement limiter**

H1 pumps are designed with optional mechanical displacement (stroke) limiters factory set to max. displacement. The maximum displacement of the pump can be set independently for forward and reverse using the two adjustment screws to mechanically limit the travel of the servo piston down to 50 % displacement.

Adjustments under operating conditions may cause leakage. The adjustment screw can be completely removed from the threaded bore if backed out to far.



Displacement change (approximately) H1P 060/068

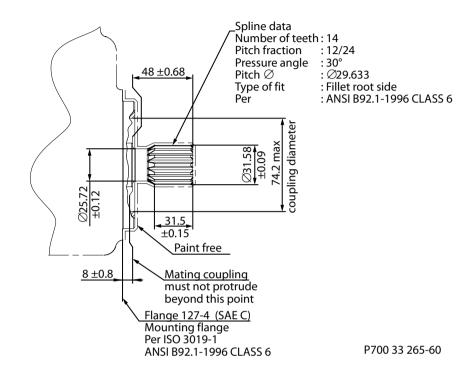
Parameter	Size 060	Size 068
1 Turn of displacement limiter screw	5.9 cm <sup>3</sup> [0.36 in <sup>3</sup> ]	6.6 cm <sup>3</sup> [0.40 in <sup>3</sup> ]
Internal wrench size	4 mm	
External wrench size	13 mm	
Torque for external hex seal lock nut	23 N·m [204 lbf•in]	

For more information, see *H1 Axial Piston Pumps, Service Manual,* **AX00000087**, the section "Displacement Limiter Adjustment".



## Input shaft, option G1 (SAE C, 14 teeth)

Option G1, ISO 3019-1, outer dia 32 mm-4 (SAE C, 14 teeth) 060/068



#### **Specifications**

Option		G1	
Spline		14 teeth, 12/24 pitch	
Min. active spline length <sup>1)</sup>		31.45 mm [1.238 in]	
Torque rating <sup>2)</sup> Rated		534 N•m [4720 lbf•in]	
Maximum		592 N•m [5240 lbf•in]	

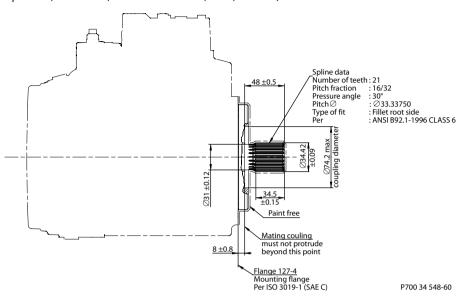
<sup>1)</sup> Minimum active spline length for the specified torque ratings.

<sup>&</sup>lt;sup>2)</sup> For definitions of maximum and rated torque values, refer to *Basic Information* **11062168**, section Shaft Torque Ratings and Spline Lubrication.



## Input shaft, option F1 (SAE C, 21 teeth) 045/053

Option F1, ISO 3019-1, outer dia 35 mm-4 (SAE C, 21 teeth)



## Specifications

Option		F1	
Spline		21 teeth, 16/32 pitch	
Min. active spline length <sup>1)</sup>		34.5 mm [1.358 in]	
Torque rating <sup>2)</sup> Rated		760 N•m [6730 lbf•in]	
Maximum		1137 N•m [10 060 lbf•in]	

 $<sup>\</sup>overline{\ ^{1)}}$  Minimum active spline length for the specified torque ratings.

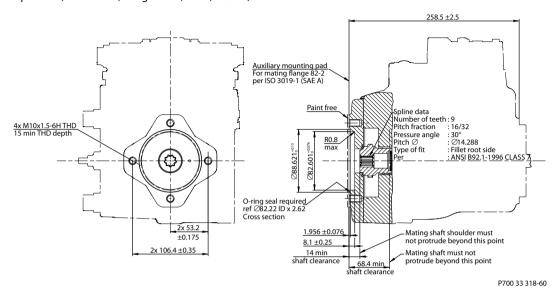
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<sup>&</sup>lt;sup>2)</sup> For definitions of maximum and rated torque values, refer to *Basic Information* **11062168**, section Shaft Torque Ratings and Spline Lubrication.



## H1P Auxiliary mounting, option H2 (SAE A, 9 teeth)

Option H2, ISO 3019-1, flange 82-2 (SAE A, 9 teeth)



### Specifications

Option	H2
Spline	9 teeth, 16/32 pitch
Maximum torque <sup>1)</sup>	162 N·m [1430 lbf·in]

<sup>&</sup>lt;sup>1)</sup> For definitions of maximum and rated torque values, refer to *Basic Information* **11062168**, section Shaft Torque Ratings and Spline Lubrication.

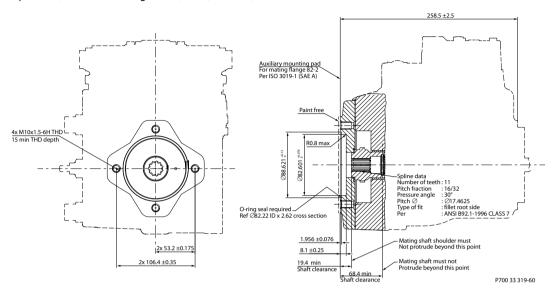


#### Caution



## H1P Auxiliary mounting, option H1 (SAE A, 11 teeth)

Option H1, ISO 3019-1, flange 82-2 (SAE A, 11 teeth)



### Specifications

Option	H1
Spline	11 teeth, 16/32 pitch
Maximum torque <sup>1)</sup>	296 N·m [2620 lbf·in]

<sup>&</sup>lt;sup>1)</sup> For definitions of maximum and rated torque values, refer to *Basic Information* **11062168**, section Shaft Torque Ratings and Spline Lubrication.

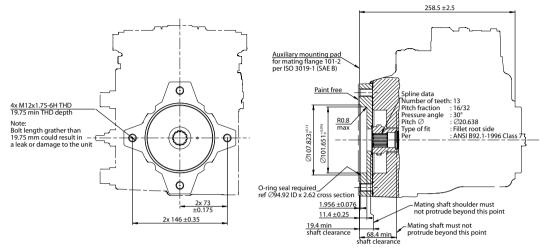


#### Caution



## H1P Auxiliary mounting, option H3 (SAE B, 13 teeth)

Option H3, ISO 3019-1, flange 101-2 (SAE B, 13 teeth)



P700 33 320-60

### Specifications

Option	Н3
Spline	13 teeth, 16/32 pitch
Maximum torque <sup>1)</sup>	395 N·m [3500 lbf·in]

<sup>&</sup>lt;sup>1)</sup> For definitions of maximum and rated torque values, refer to *Basic Information* **11062168**, section Shaft Torque Ratings and Spline Lubrication.

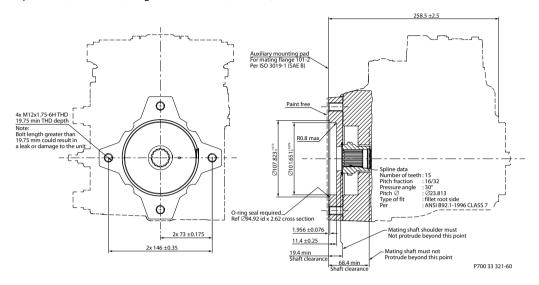


#### Caution



## H1P Auxiliary mounting, option H5 (SAE B-B, 15 teeth)

Option H5, ISO 3019-1, flange 101-2 (SAE B-B, 15 teeth)



#### Specifications

Option	H5
Spline	15 teeth, 16/32 pitch
Maximum torque <sup>1)</sup>	693 N·m [6130 lbf·in]

<sup>&</sup>lt;sup>1)</sup> For definitions of maximum and rated torque values, refer to *Basic Information* **11062168**, section Shaft Torque Ratings and Spline Lubrication.

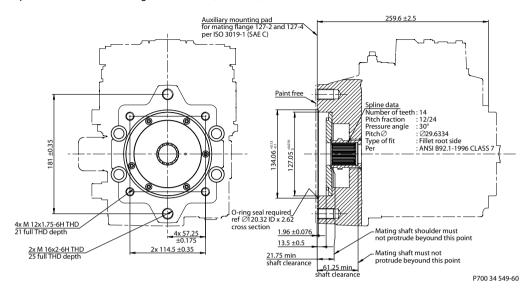


#### Caution



## H1P Auxiliary mounting, option H6 (SAE C, 14 teeth)

Option H6, ISO 3019-1, flange 127-4 (SAE C, 14 teeth)



#### Specifications

Option	H6
Spline	14 teeth, 12/24 pitch
Maximum torque <sup>1)</sup>	816 N·m [7220 lbf·in]

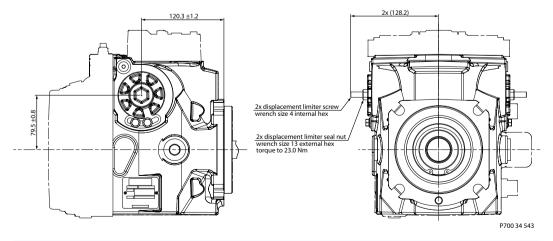
<sup>1)</sup> For definitions of maximum and rated torque values, refer to *Basic Information* **11062168**, section Shaft Torque Ratings and Spline Lubrication.



## Caution

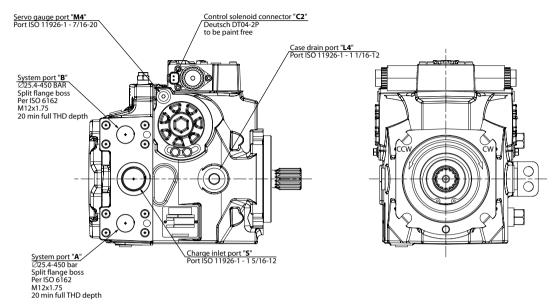
Standard pad cover is installed only to retain coupling during shipping. Do not operate pump without an auxiliary pump or running cover installed.

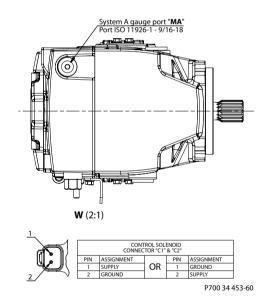
### H1P 060/068 displacement limiter, option B



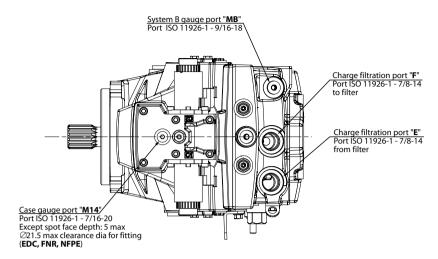


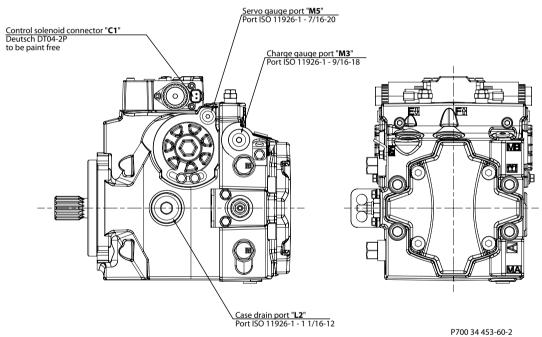
# Port description H1P 060/068





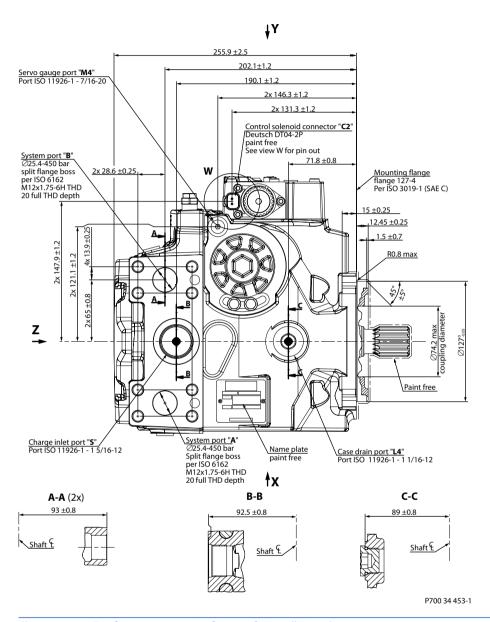




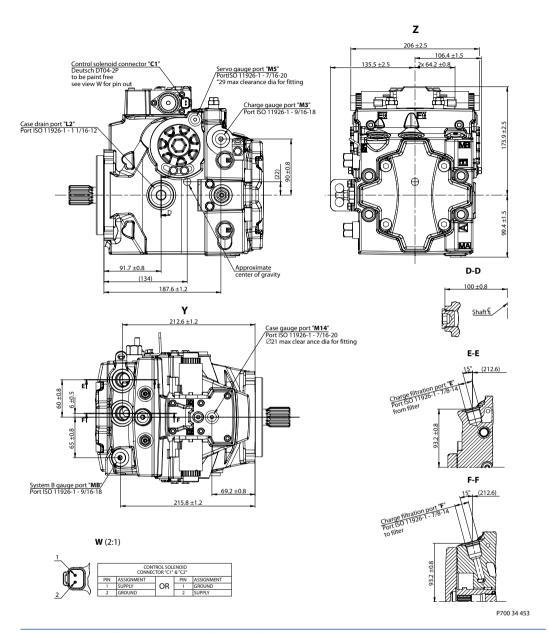




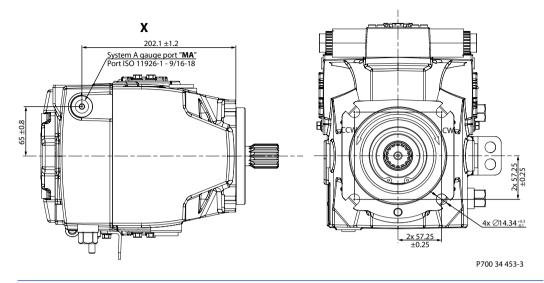
## Dimensions H1P 060/068





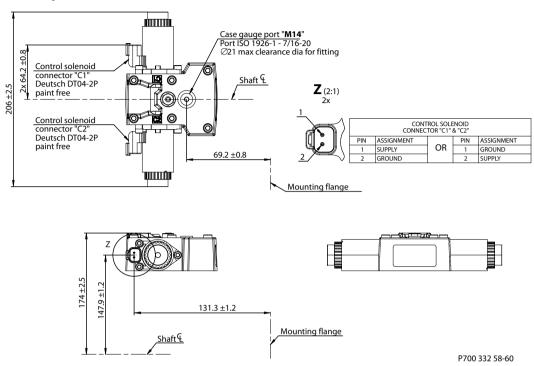






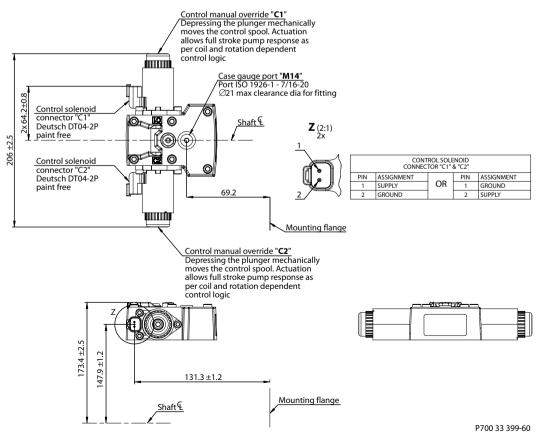


## Electric Displacement Control (EDC), options: A2 (12 V) / A3 (24 V)



Please contact Danfoss representative for specific installation drawings.

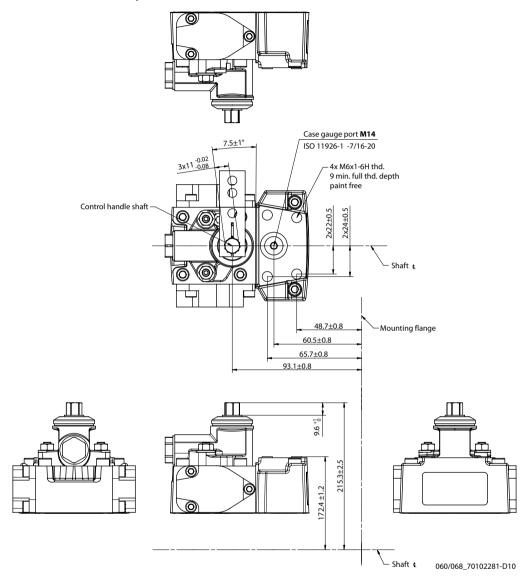
## Electric Displacement Control (EDC) with MOR, options: A4 (12 V) / A5 (24 V)





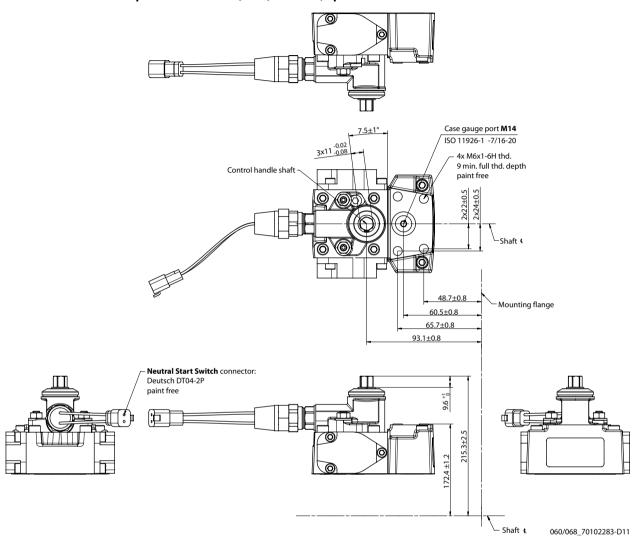
Please contact Danfoss representative for specific installation drawings.

## H1P 060/068 Manual Displacement Control (MDC), option M1





# H1P 060/068 Manual Displacement Control (MDC) with NSS, option M2

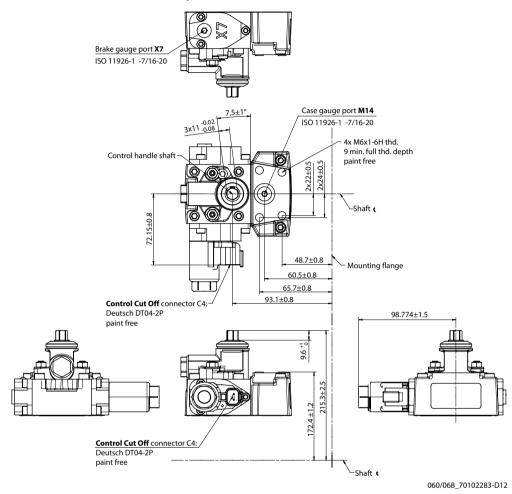


#### **Neutral Start Switch connector:**

Pin	Assignment		Pin	Assignment
1	Supply	OR	1	Ground
2	Ground		2	Supply



# H1P 060/068 Manual Displacement Control (MDC) with CCO, option M3, M4

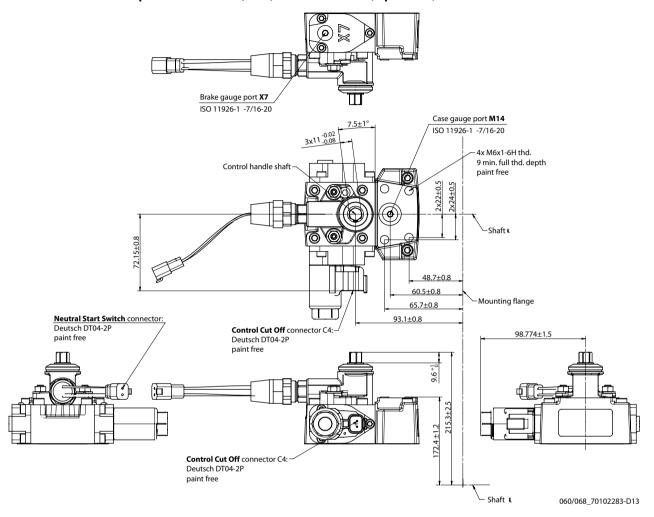


#### Control Cut Off connector C4:

Pin	1	Assignment		Pin	Assignment
1		Supply	OR	1	Ground
2		Ground		2	Supply



# H1P 060/068 Manual Displacement Control (MDC) with NSS and CCO, option M5, M6

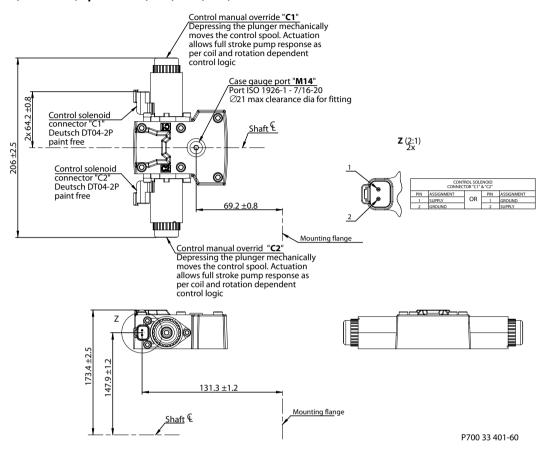


Neutral Start Switch connector / Control Cut Off connector C4:

Pin	Assignment		Pin	Assignment
1	Supply	OR	1	Ground
2	Ground		2	Supply

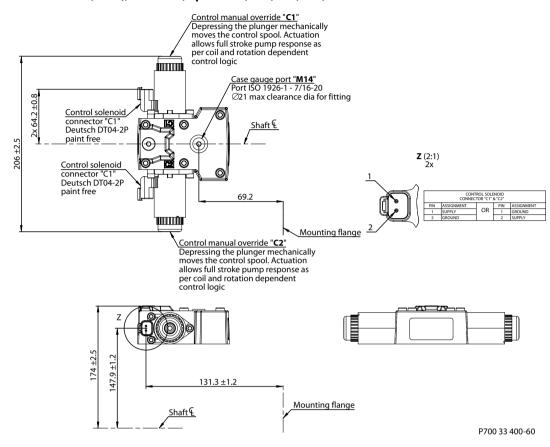


## Forward-Neutral-Reverse (FNR) with MOR, options: A9 (12 V) / B1 (24 V)



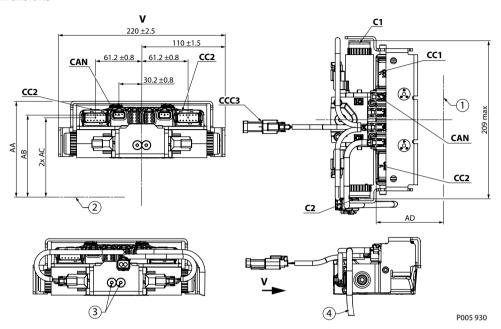


## Non Feedback Proportional Electric control (NFPE), with MOR, option A8 (12 V)/B8 (24 V)





# **Automotive Control (AC) Dimensions**



- 1. Mounting flange
- 2. Shaft
- 3. Plug removing can cause contamination issues
- **4.** PPU wire harness is factory installed to speed sensor

### Dimensions, (mm)

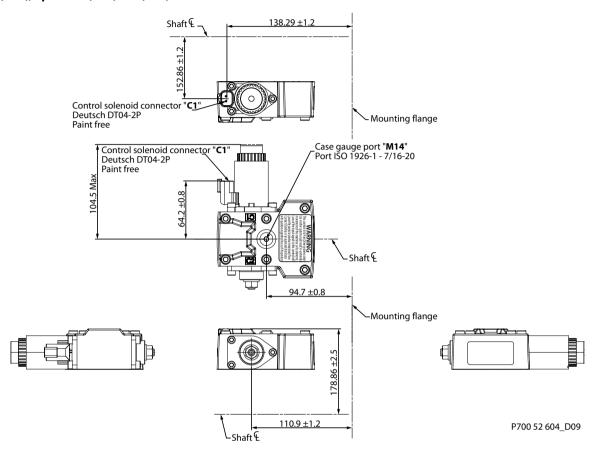
Callout	Value
AA	208.9 ±2.5
АВ	190.5 ±1.2
AC	2x 187.1 ±1.2
AD	89.2 ±1.2

## Connectors description

Port	Description
C1 C2	Control MOR; Depressing the plunger mechanically moves the control spool. Actuation allows full stroke pump response as per coil and rotation dependent control logic.
CC1	Control connector Deutsch DTM04-12P -A; Paint free
CC2	Control connector Deutsch DTM04-12P -B; Paint free
СССЗ	Control connector Deutsch DT06-2S; Paint free; For using connector the plug may be removed.
CAN	Control connector Deutsch DTM04-3P; Paint free; For using connector the plug may be removed.



# Fan Drive Control (FDC), option F1 (12V) / F2 (24V)

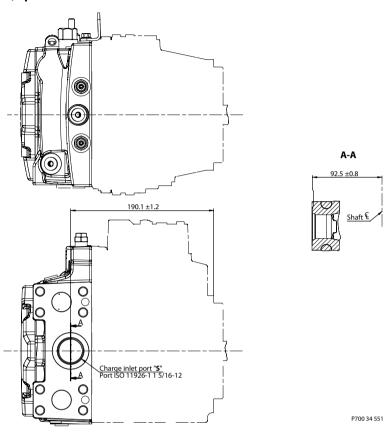


#### Control solenoid connector C1 and C2:

Pin	Assignment	Alternative	Pin	Assignment
1	Supply	OR	1	Ground
2	Ground		2	Supply

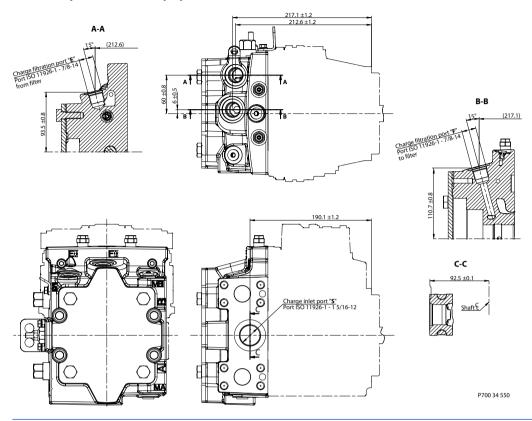


# H1P 060/068, suction filtration, option L





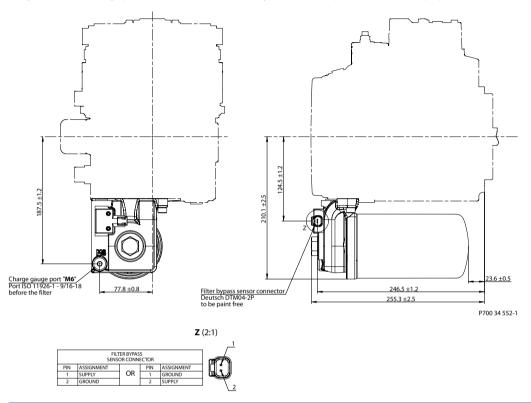
# Remote full charge pressure filtration, option P for end cap option F (SAE-C PTO)





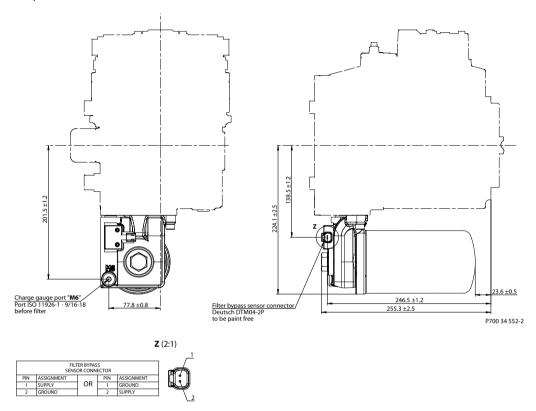
# Integral full flow charge pressure filtration with filter bypass sensor, options M / D3, F4

Integral full flow charge pressure filtration with filter bypass sensor, option M, for end cap option D3





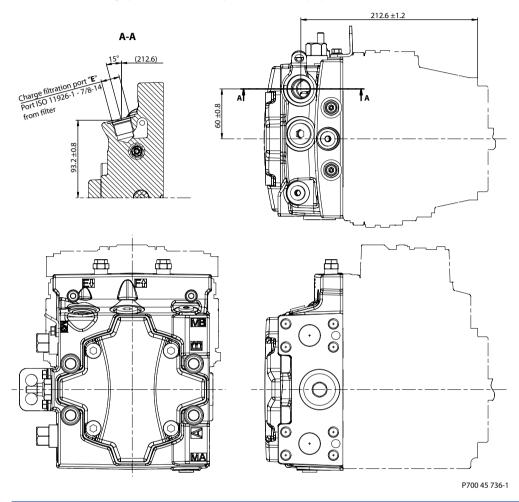
Integral full flow charge pressure filtration with filter bypass sensor, option M, for end cap <u>option F4</u> (SAE-C PTO)





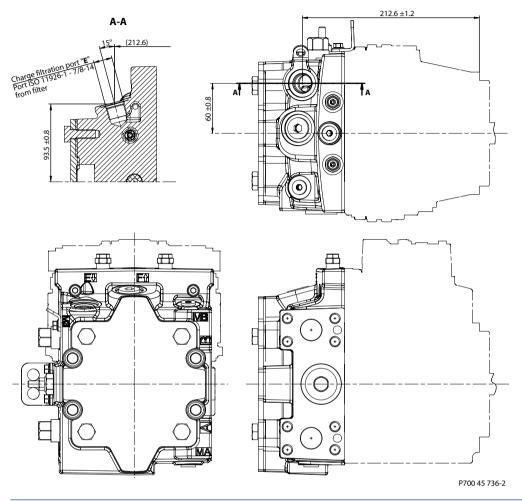
# External full flow charge pressure filtration, option E / D8, F5

External full flow charge pressure filtration, option E for end cap option D8





External full flow charge pressure filtration, option E for end cap option F5 (SAE-C PTO)













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